

## Classification

The highest order of derivative appearing in a differential equation is referred to as its **order**.

Ex :  $d^2y/dx^2 + (dy/dx)^3 + y = 0$  – is a second order differential equation.

The power of the highest order derivative term is known as its **degree**.

The degree of the above differential equation is 1.

Ex :  $(dy/dx)^3 + y = 0$

The order of the above differential equation is 1, but its degree is 3.

**If the powers of the dependent variable and all its derivatives are ‘1’**, the differential equation is called **linear**, otherwise it is non-linear.

Ex :  $d^2y/dx^2 + 2x dy/dx + ny = x^2$  – is a linear differential equation, but the equation :  
 $d^2y/dx^2 + 2x dy/dx + ny = y^2$  – is non-linear.

If the differential equation has a term, independent of the dependent variable and its derivatives, the differential equation is called **inhomogeneous**. This term is usually placed on the right hand side and called the source term. If no such term is present, the equation is homogeneous.

Ex : the diff. eqn. of a forced, damped harmonic oscillator :

$m d^2x/dt^2 + 2b dx/dt + kx = A \sin \omega t$  – is inhomogeneous and the source term is the RHS.

the diff. eqn. of a free, damped harmonic oscillator :

$m d^2x/dt^2 + 2b dx/dt + kx = 0$  – is homogeneous.

The diff. eqn.  $m d^2x/dt^2 + 2b dx/dt + kx = \alpha x^2$  – is however not inhomogeneous; rather, it is non-linear and usually written as :  $m d^2x/dt^2 + 2b dx/dt + kx - \alpha x^2 = 0$ .

If the coefficients of the dependent variable and all its derivatives are constants, the differential equation is said to have **constant coefficients**.

Ex :  $d^2x/dt^2 + 4 dx/dt + 5x = 0$  – is a differential equation with constant coefficients.

$x^2 d^2y/dx^2 + 2x dy/dx + 5y = 0$  – is a differential equation with non-constant coefficients.

$d^2y/dx^2 + 2y dy/dx + 5y = 0$  – is however a non-linear differential equation.

### **First order Liner Equations :**

The most general form of such equations is :  $a(x) dy/dx + b(x) y + c(x) = 0$ , which may be recast in the form :

$$dy/dx + P(x) y = Q(x), \text{ provided of course, } a(x) \neq 0.$$

**Let us first consider the simple case where P(x) is a constant = p.**

Note that :  $d/dx \{e^{px} y\} = e^{px} dy/dx + p e^{px} y = e^{px} \{dy/dx + py\}$

Thus, if we multiply  $\{dy/dx + py\}$  by  $e^{px}$ , the result becomes a total derivative of  $\{e^{px} y\}$ .

The factor  $e^{px}$  is called an **Integrating Factor (I.F.)**.

In a more general case, where P(x) is not a constant, **I.F. =  $\exp\{\int P(x) dx\}$** . Let's take an example :

Find the I.F. for :  $dy/dx + x y$

Clearly, P(x) = x, here. So.  $\int P(x) dx = x^2/2 \Rightarrow$  I.F. =  $\exp(x^2/2)$ . Now check :

$$\exp(x^2/2) dy/dx + \exp(x^2/2) x y = d/dx \{\exp(x^2/2) y\}$$

How does it help ? Take another example :

Solve :  $dy/dx + y/x = x^n$

I.F. =  $\exp\{\int 1/x dx\} = \exp\{\ln x\} = x$ . Multiplying both sides by x :  $x dy/dx + y = x^{n+1}$

LHS is expected to become a total derivative, which indeed it is !  $x dy/dx + y = d/dx (xy)$

Thus,  $d/dx (xy) = x^{n+1} \Rightarrow xy = x^{n+2}/(n+2) + C \Rightarrow y = x^{n+1}/(n+2) + C/x$

Another example : Solve  $dy/dx + xy = x$

I.F. =  $\exp\{\int x dx\} = \exp\{x^2/2\}$ . Multiplying both sides by I.F. :

$$\begin{aligned} \exp\{x^2/2\} dy/dx + x \exp\{x^2/2\} y &= x \exp\{x^2/2\} \\ \Rightarrow d/dx \{ \exp(x^2/2) y \} &= x \exp\{x^2/2\} \\ \Rightarrow \{ \exp(x^2/2) y \} &= \int x \exp\{x^2/2\} dx. \end{aligned}$$

RHS can be integrated by substituting  $x^2/2 = z \Rightarrow x dx = dz$ ,  
so that RHS becomes :  $\int e^z dz = e^z = \exp\{x^2/2\}$

$$\text{Thus, } \{ \exp(x^2/2) y \} = \exp\{x^2/2\} + C \Rightarrow y = 1 + C \exp\{-x^2/2\}$$

- Do not forget to include the arbitrary constant 'C'. It's a small crime in case of ordinary integration, but a serious crime in case of a differential equation. Besides, you may miss a major part of the solution (not just a constant term), as case of the example above.
- One might ask why we skipped 'C' while finding the I.F. then ? The answer is : it doesn't matter !  $\exp\{ \int P(x) dx + C \} = e^C \exp\{ \int P(x) dx \} = A \exp\{ \int P(x) dx \}$  and the constant 'A' drops from both sides.
- One might worry that after multiplying by the I.F., the RHS may become difficult to integrate. This indeed may happen, but that is an *integration problem*. We have essentially solved the differential equation ! Technically, one says, 'we have reduced it to quadrature'.

### Second Order, Homogeneous, Linear Differential Equation with Constant Coefficients

The differential eqn. is of the form :

$$\mathbf{a \, d^2y/dx^2 + b \, dy/dx + c \, y = 0} \quad \text{---- (1)}$$

$$\text{Try : } y = e^{mx} \Rightarrow dy/dx = m e^{mx} \Rightarrow d^2y/dx^2 = m^2 e^{mx}$$

$$\begin{aligned} \text{Substituting in the differential eqn. we get : } (a \, m^2 + b \, m + c) e^{mx} &= 0 \\ \Rightarrow a \, m^2 + b \, m + c &= 0 \end{aligned}$$

The above equation is an algebraic equation which is known as the **Auxiliary Equation**. We are to solve this to find the values of m for which  $e^{mx}$  satisfies the differential eqn.

So, we have reduced the task of solving a differential equation to one of solving an algebraic equation. Let the two roots of the auxiliary eqn. be  $m_1$  and  $m_2$ . Then  $y = \exp(m_1 x)$  and  $y = \exp(m_2 x)$  are two solutions.

**Theorem** : if  $y_1, y_2, y_3$  etc., are solutions of a **Homogeneous, Linear** differential equation, then  $(A y_1 + B y_2 + C y_3 + \dots)$  is also a solution of the same eqn., where A, B, C, etc., are arbitrary constants.

$$\begin{aligned} \text{Proof :} \quad A \times [a \, d^2y_1/dx^2 + b \, dy_1/dx + c \, y_1] &= 0 \\ B \times [a \, d^2y_2/dx^2 + b \, dy_2/dx + c \, y_2] &= 0 \\ \text{Adding : } a \, d^2/dx^2 (A y_1 + B y_2) + b \, d/dx (A y_1 + B y_2) + c (A y_1 + B y_2) &= 0 \end{aligned}$$

**Theorem** : if  $y_1, y_2$  are two linearly independent\* solutions of a **2nd order, Homogeneous, Linear** differential equation, then  $(A y_1 + B y_2)$  is the general solution of the differential equation, where A and B are arbitrary constants.

**\*Linear independence means :  $(A y_1 + B y_2) = 0$  guarantees  $A = 0, B = 0$ .**

Case I ( $b^2 > 4ac$ ) : Here  $m_1$  and  $m_2$  are two real and distinct roots of the auxiliary eqn. The roots are unequal, which means that  $\exp(m_1 x)$  and  $\exp(m_2 x)$  are linearly independent solutions.

Hence,  $y = \mathbf{A \, \exp(m_1 x) + B \, \exp(m_2 x)}$  is the general solution.

Case II ( $b^2 < 4ac$ ) : Here  $m_1$  and  $m_2$  are complex and of the form :  $m_1 = (\alpha + i\beta)$ ,  $m_2 = (\alpha - i\beta)$ . These are also unequal, hence  $\exp(m_1 x)$  and  $\exp(m_2 x)$  are linearly independent

solutions. So the general solution is of the form :

$$\begin{aligned} y &= Ae^{(\alpha + i\beta)x} + Be^{(\alpha - i\beta)x} = e^{\alpha x} (Ae^{i\beta x} + Be^{-i\beta x}) \\ &= e^{\alpha x} [ A\{\cos \beta x + i \sin \beta x\} + B\{\cos \beta x - i \sin \beta x\}] \\ &= e^{\alpha x} [ C \cos \beta x + D \sin \beta x] \end{aligned}$$

where  $C = (A + B)$  and  $D = i(A - B)$  are another set of arbitrary constants.

Case III ( $b^2 = 4ac$ ): Here the roots are equal,  $m_1 = m_2 = m$  (say), where  $m = (-b/2a)$ .

Now the two solutions  $\exp(m_1x)$  and  $\exp(m_2x)$  are identical and cannot be combined to form the general solution.

$$y = Ae^{mx} + Be^{mx} = (A + B) e^{mx} = Ce^{mx},$$

where  $C$  is just another constant.

To obtain another linearly independent solution, try :

$$y = e^{mx} f(x)$$

$$\Rightarrow dy/dx = m e^{mx} f(x) + e^{mx} f'(x)$$

$$\Rightarrow d^2y/dx^2 = m^2 e^{mx} f(x) + 2m e^{mx} f'(x) + e^{mx} f''(x)$$

Substituting in the differential equation (1) :

$$a e^{mx} [m^2 f(x) + 2mf'(x) + f''(x)] + b e^{mx} [m f(x) + f'(x)] + c e^{mx} f(x) = 0$$

$$\Rightarrow a [m^2 f(x) + 2mf'(x) + f''(x)] + b [m f(x) + f'(x)] + c f(x) = 0,$$

but  $am^2 + bm + c = 0$ , since  $m$  is the solution of the auxiliary equation

and also  $2am + b = 0$ , since, when  $b^2 = 4ac$ ,  $m = (-b/2a)$ .

$$\text{Hence, } f''(x) = 0$$

$$\Rightarrow f(x) = Ax + C$$

Thus,  $y = e^{mx} f(x) = e^{mx} (Ax + C)$  is the general solution.

[The solution  $Ce^{mx}$  obtained at first, is absorbed in the second term above.]

### Wronskian

If  $y_1(x)$  and  $y_2(x)$  are two solutions of a Linear, homogeneous differential equation, then the solutions are called **linearly dependent**, if there exists a non-trivial (not all zero) pair of coefficients  $c_1$  and  $c_2$ , such that :

$$c_1 y_1 + c_2 y_2 = 0$$

Differentiating, we get :

$$c_1 y_1' + c_2 y_2' = 0$$

We can write this pair of equations in the matrix form as :

$$\begin{bmatrix} y_1 & y_2 \\ y_1' & y_2' \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

For a non-trivial solution for  $c_1$  and  $c_2$ , we must have :  $\det \begin{bmatrix} y_1 & y_2 \\ y_1' & y_2' \end{bmatrix} = 0$ ,

$$\text{i.e., } (y_1 y_2' - y_2 y_1') = 0.$$

If, on the other hand, the determinant is non-zero, then the only choice left is :  $c_1 = c_2 = 0$   
 $y_1, y_2$  are called **linearly independent**. The determinant mentioned above is called the **Wronskian  $W(x)$** . The concept may easily be generalized to 'n' number of solutions.

Let us consider the differential equation :

$$a(x) d^2y/dx^2 + b(x) dy/dx + c(x) y = 0,$$

which has two solutions :  $y_1(x)$  and  $y_2(x)$ . We must have :

$$a(x) y_1'' + b(x) y_1' + c(x) y_1 = 0$$

$$\text{and } a(x) y_2'' + b(x) y_2' + c(x) y_2 = 0$$

Multiplying the first equation by  $y_2$  and the second equation by  $y_1$  and subtracting, we obtain :

$$\begin{aligned} a(x) (y_1''y_2 - y_2''y_1) + b(x) (y_1'y_2 - y_2'y_1) &= 0 \\ \text{i.e., } a(x)W'(x) + b(x)W(x) &= 0 \\ \Rightarrow W'(x)/W(x) &= -b(x)/a(x) \\ \Rightarrow \int dW/W &= -\int b(x)/a(x) dx \\ \Rightarrow W(x) &= A \exp \left[ -\int b(x)/a(x) dx \right] \text{ ---- (1)} \end{aligned}$$

### To find the second solution :

If one of the solutions  $y_1(x)$  of a second order, homogeneous, linear differential equation is known, then a second solution  $y_2(x)$  may be found with the help of the Wronskian function.

The Wronskian  $W(x)$  of these two function, by definition, is :  $y_1 y_2' - y_2 y_1'$

We view it as a differential equation for  $y_2(x)$  :

$$\begin{aligned} y_1(x) \frac{dy_2}{dx} - y_1'(x) y_2 &= W(x) \\ \Rightarrow \frac{dy_2}{dx} - (y_1'/y_1) y_2 &= W/y_1 \end{aligned}$$

This is clearly, a first order, linear, inhomogeneous differential equation in  $y_2$ .

The Integrating factor is :  $\exp \left( -\int y_1'/y_1 dx \right) = \exp \left( -\ln y_1 \right) = 1/y_1$

Multiplying by this factor, we get :

$$\begin{aligned} (1/y_1) \frac{dy_2}{dx} - (y_1'/y_1^2) y_2 &= W/y_1^2 \\ \Rightarrow \frac{d}{dx} (y_2/y_1) &= W/y_1^2 \\ \Rightarrow (y_2/y_1) &= \int (W/y_1^2) dx \\ \Rightarrow y_2(x) &= y_1(x) \int (W/y_1^2) dx \text{ ---- (2)} \end{aligned}$$

### Example :

Consider the differential equation :  $d^2y/dx^2 - 2b dy/dx + b^2 y = 0$ .

The trial  $y = e^{mx} \Rightarrow m = b$ . So we easily find a solution :  $y_1(x) = e^{bx}$

The Wronskian for this differential equation is :  $W(x) = A \exp \left[ + \int 2b dx \right] = A e^{2bx}$  [by (1)]

Hence, a second solution is :  $e^{bx} \int Ae^{2bx} / e^{2bx} [by (2)] = e^{bx} \times Ax$ , as we found earlier.

### Second Order, In-homogeneous, Linear Differential Equation with Constant Coefficients

The differential eqn. is of the form :

$$a \frac{d^2y}{dx^2} + b \frac{dy}{dx} + c y = f(x), \text{ ---- (1)}$$

where  $f(x)$  is sometimes called the 'source term'. Our task will be to find a general solution of this eqn.

**Theorem** : if  $y_0(x)$  is the general solution of the **homogeneous** equation corresponding to (1) and  $y_1(x)$  is any one particular solution of the full, inhomogeneous eqn. (1), then  $y_0(x) + y_1(x)$  will be **the general solution of the of the full, inhomogeneous eqn. (1)**.

We call  $y_0(x)$  the **complementary function (C.F.)** and  $y_1(x)$  the **Particular Integral function (P.I.)**. The C.F. part will naturally involve two arbitrary constants. We have already learnt to find out the solution of a homogeneous eqn. So, we focus on finding the P.I.

We denote the operator 'd/dx' by 'D', so that our eqn. (1) may be written as :

$$\begin{aligned} [a D^2 + b D + c] y &= f(x) \\ \Rightarrow y &= \{ 1/[a D^2 + b D + c] \} f(x), \text{ or, } [a D^2 + b D + c]^{-1} f(x) \end{aligned}$$

This is of course, a formal way of writing, because  $[a D^2 + b D + c]$  is an operator and not a number. Actually,  $[a D^2 + b D + c]^{-1}$  means the inverse of the operator.

$$1) \quad f(x) = e^{px}$$

Note that  $D e^{px} = d/dx (e^{px}) = p e^{px}$

$$\Rightarrow D^2 e^{px} = p^2 e^{px}, \text{ etc.,}$$

which shows that while acting on  $e^{px}$ , the operator 'D' may be simply replaced by p

If  $\mathbf{A} f(x) = \lambda f(x)$ , where  $\mathbf{A}$  is an operator, but  $\lambda$  is a number, then  $f(x)$  is called the '**eigen function**' of  $\mathbf{A}$ , corresponding to the '**eigenvalue**'  $\lambda$ .

$$\text{Thus, P.I.} = 1/ [aD^2 + bD + c] e^{px} = 1/ [ap^2 + bp + c] e^{px}$$

## 2) $f(x) = \sin px$ , or, $\cos px$

$$D \sin px = p \cos px \Rightarrow D^2 \sin px = (-p^2) \sin px,$$

$$D \cos px = -p \sin px \Rightarrow D^2 \cos px = (-p^2) \cos px,$$

which means, that  $\sin px$ , or,  $\cos px$  are not eigen functions of D, but they are eigen functions of  $D^2$ . If our differential eqn. involves only even powers of D, i.e.,  $D^2, D^4$ . etc., we can replace  $D^2$  by  $(-p^2)$ . For example, if

$$a \frac{d^2y}{dx^2} + c y = \sin px,$$

$$\text{then P.I.} = 1/ [aD^2 + c] \sin px = 1/ [-ap^2 + c] \sin px$$

If however odd powers of 'D' are involved, we have to '**rationalize**'. For example, if

$$a \frac{d^2y}{dx^2} + b \frac{dy}{dx} + c y = \cos px,$$

$$\text{then } 1/ [aD^2 + bD + c] \text{ is written as : } [(aD^2 + c) - bD] / [(aD^2 + c) + bD] [(aD^2 + c) - bD]$$
$$= [(aD^2 + c) - bD] / [(aD^2 + c)^2 - (bD)^2]$$

$$\text{Hence P.I.} = [(aD^2 + c) - bD] / [(aD^2 + c)^2 - (bD)^2] \cos px$$
$$= [(aD^2 + c) - bD] \cos px / [(-ap^2 + c)^2 + b^2p^2]$$
$$= [(-ap^2 + c) \cos px - bp \sin px] / [(-ap^2 + c)^2 + b^2p^2]$$

Example :

$$d^2y/dx^2 + 2 dy/dx + 3 y = \cos 2x$$

$$\Rightarrow \text{P.I.} = 1/ [D^2 + 2D + 3] \cos 2x$$
$$= [(D^2 + 3) - 2D] / [(D^2 + 3)^2 - (2D)^2] \cos 2x$$
$$= [(D^2 + 3) - 2D] \cos 2x / [(-4 + 3)^2 + 16]$$
$$= [(-4 + 3) \cos 2x + 4 \sin 2x] / 17$$
$$= [(-4 + 3) \cos 2x + 4 \sin 2x] / 17.$$

## 3) $f(x) = A + Bx + Cx^2 + \dots$ [A polynomial in x]

$1/(aD^2 + bD + c)$  may be written as :

$$1/[c (aD^2/c + bD/c + 1)]$$

$$= 1/c \times 1/[1 + (bD/c + aD^2/c)]$$

$$= 1/c \times [1 + (bD/c + aD^2/c)]^{-1}$$

$$= 1/c [1 - (bD/c + aD^2/c) + (bD/c + aD^2/c)^2 - \dots]$$

$$[ \text{Since, } (1 + x)^{-1} = 1 - x + x^2 - \dots ]$$

$$\text{So, } 1/[aD^2 + bD + c] (A + Bx + Cx^2 + \dots)$$

$$= 1/c [1 - (bD/c + aD^2/c) + (bD/c + aD^2/c)^2 - \dots] (a + bx + cx^2 + \dots)$$

Now, powers of D (i.e., d/dx) will act on powers of x and the result will vanish whenever the power of 'D' is higher. So, the series will eventually terminate. Let us clarify the procedure with an example :

**[If you feel the above steps to be complicated, skip them and look at the example below]**

Example :

$$d^2y/dx^2 + 2 dy/dx + 3 y = 1 + 2x$$

$$1/ [D^2 + 2D + 3] (1 + 2x)$$

$$\begin{aligned}
&= 1/[3 (D^2/3 + 2D/3 + 1)] \\
&= 1/3 \times 1/[1 + (2D/3 + D^2/3)] \\
&= 1/3 \times [1 + (2D/3 + D^2/3)]^{-1} \\
&= 1/3 [1 - (2D/3 + D^2/3) + (2D/3 + D^2/3)^2 - \dots] \\
\Rightarrow \text{P.I.} &= 1/3 [1 - (2D/3 + D^2/3) + (2D/3 + D^2/3)^2 - \dots] (1 + 2x) \\
&= 1/3 [1 - 2D/3] (1 + 2x) \text{ [Since the higher powers of } D \text{ kills the function]} \\
&= 1/3 (1 + 2x) - (2D/9) (2x) = \mathbf{1/3 (1 + 2x) - 4/9 = 2x/3 - 1/9.}
\end{aligned}$$

**4)  $f(x) = e^{px} V(x)$**

$$\begin{aligned}
D f(x) &= p e^{px} V(x) + e^{px} D V(x) = e^{px} (p + D) V(x) \\
D^2 f(x) &= \{p^2 e^{px} V(x) + p e^{px} D V(x)\} + \{p e^{px} D V(x) + e^{px} D^2 V(x)\} \\
&= e^{px} \{p^2 V(x) + 2p D V(x) + D^2 V(x)\} \\
&= e^{px} (p + D)^2 V(x) \\
&\dots \dots \dots
\end{aligned}$$

$$D^n f(x) = e^{px} (p + D)^n V(x)$$

We can apply this rule in problems like :  $d^2y/dx^2 + 2 dy/dx + 3 y = e^x x^2$   
However, the above rule has interesting applications in some special cases of type - 1) and type - 2) problems

Example of type 1:

$$\begin{aligned}
d^2y/dx^2 - 5 dy/dx + 6 y &= e^{2x} \\
y &= 1/(D^2 - 5 D + 6) e^{2x} = 1/(D - 3)(D - 2) e^{2x}
\end{aligned}$$

Following the standard prescription, you cannot substitute '2' for 'D'.

$$\begin{aligned}
\text{Re-write : } d^2y/dx^2 - 5 dy/dx + 6 y &= e^{2x} \times \mathbf{1} \\
(D^2 - 5 D + 6) y &= e^{2x} \mathbf{1}
\end{aligned}$$

$$\begin{aligned}
\Rightarrow y &= 1/(D^2 - 5D + 6) e^{2x} \mathbf{1} \\
&= e^{2x} 1/[(D+2)^2 - 5 (D+2) + 6] \mathbf{1} \text{ ---- [ by rule (4) ]} \\
&= e^{2x} 1/[(D^2 + 4D + 4) - 5D - 10 + 6] \mathbf{1} \\
&= e^{2x} 1/[D^2 - D] \mathbf{1} \\
&= e^{2x} 1/[(D - 1) D] \mathbf{1} = e^{2x} 1/[D - 1] x \text{ ---- [ since } 1/D \text{ is nothing but } \int dx \text{ ]} \\
&= -e^{2x} 1/[1 - D] x = -e^{2x} [1 - D]^{-1} x = -e^{2x} [1 + D + D^2 + \dots] x \\
&= \mathbf{-e^{2x} [x + 1]}
\end{aligned}$$

Example of type 2:

$$d^2y/dt^2 + \omega^2 y = \sin \omega t$$

[ This is the forced harmonic oscillator without damping at resonance freq.]

$$y = 1/[D^2 + \omega^2] \sin \omega t, \text{ [Here } D = \text{stands for } d/dt]$$

You cannot replace  $D^2$  by  $(-\omega^2)$ . Following the standard prescription.

Now  $(\sin \omega t)$  is the imaginary part of  $(e^{i\omega t})$ . So, write :

$$y = \mathbf{Im} \{ 1/[D^2 + \omega^2] e^{i\omega t} \}$$

You still cannot replace  $D$  by  $(i\omega)$ . So apply technique 4). Write :

$$\begin{aligned}
y &= \mathbf{Im} \{ 1/[D^2 + \omega^2] e^{i\omega t} \times \mathbf{1} \} \\
&= \mathbf{Im} \{ e^{i\omega t} \times 1/[(D + i\omega)^2 + \omega^2] \mathbf{1} \} \\
&= \mathbf{Im} \{ e^{i\omega t} \times 1/[D^2 + 2i\omega D] \mathbf{1} \} \\
&= \mathbf{Im} \{ e^{i\omega t} \times 1/[D + 2i\omega] t \} \text{ ---- [since, } [1/D] \mathbf{1} = t \text{]} \\
&= \mathbf{Im} \{ e^{i\omega t}/2i\omega \times 1/[1 + D/2i\omega] t \}
\end{aligned}$$

$$\begin{aligned}
&= \mathbf{Im} \left\{ e^{i\omega t} / 2i\omega \times [1 - D/2i\omega + \dots] t \right\} \\
&= \mathbf{Im} \left\{ e^{i\omega t} / 2i\omega \times [t - 1/2i\omega] \right\} = \mathbf{Im} \left\{ e^{i\omega t} \times [t/2i\omega + 1/4\omega^2] \right\} \\
&= \mathbf{Im} \left\{ (\cos \omega t + i \sin \omega t) (t/2i\omega + 1/4\omega^2) \right\} = (\mathbf{sin} \omega t / 4\omega^2) - (t \mathbf{cos} \omega t / 2\omega)
\end{aligned}$$

Substituting in the diff. eqn. :

$$\begin{aligned} & a [m^2 e^{mx} f(x) + 2m e^{mx} f'(x) + e^{mx} f''(x)] \\ & + b [m e^{mx} f(x) + e^{mx} f'(x)] \\ & + c e^{mx} f(x) = 0 \end{aligned}$$

$$\Rightarrow e^{mx} f''(x) [am^2 + bm + c] + e^{mx} f'(x) [2am + b] + c e^{mx} f(x) = 0$$

Note that :  $m = (-b/2a) \Rightarrow [2am + b] = 0$ , also  $[am^2 + bm + c] = 0$

$$\Rightarrow f''(x) = 0 \Rightarrow f'(x) = C \Rightarrow f(x) = Cx + D$$

Thus,  $y = e^{mx} (\mathbf{Cx} + \mathbf{D})$  is the general solution.

Note that the general form includes the solution  $e^{mx}$ .