

Maxima – Minima

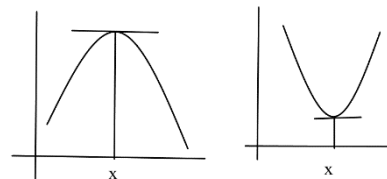
Function of a single variable

One dimensional Taylor Expansion :

If we know the values of a function $f(x)$, along with its derivatives, at a point 'x', then Taylor expansion gives us the value of the function at a neighbouring point $(x + h)$:

$$f(x + h) = f(x) + h f'(x) + \frac{h^2}{2!} f''(x) + \frac{h^3}{3!} f'''(x) + \dots$$

If the function has a (local) maximum or minimum at a point 'x' then the value of the function should be locally stationary. i.e. $f(x)$ should be equal to $f(x + h)$ for a small 'h'. This implies : **$f'(x) = 0$ up to 1st order in h.** Pictorially also, one can see that the tangent at the point 'x' is parallel to the x-axis.



Now, **up to 2nd order in h :**

$$f(x + h) = f(x) + \frac{h^2}{2!} f''(x) \quad [\text{since } f'(x) = 0]$$

If the point 'x' is a maximum, we require $f(x + h) < f(x)$ for both +ve and -ve 'h'. This implies : **$f''(x) < 0$.**

Similarly, if the point 'x' is a minimum, we require $f(x + h) > f(x)$ for both +ve and -ve 'h', which implies : **$f''(x) > 0$.**

Thus, condition for **Maximum** is : **$f'(x) = 0, f''(x) < 0$**

and condition for **Minimum** is : **$f'(x) = 0, f''(x) > 0$**

If, however, $f''(x) = 0$, we need to go to higher orders. **Up to 3rd order in h :**

$$f(x + h) = f(x) + \frac{h^3}{3!} f'''(x) \quad [\text{since } f'(x) = 0, f''(x) = 0]$$

Now, we find that, if **$f'''(x) > 0$** , then $f(x + h) > f(x)$ for +ve 'h'
and $f(x + h) < f(x)$ for -ve 'h'

The situation gets reversed if **$f'''(x) < 0$** .

Thus **$f(x)$ has neither a maximum nor a minimum** at x. It is called a '**Point of inflection**'.

The general prescription is thus as follows :

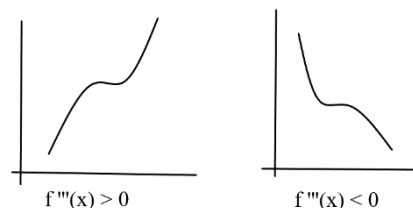
Keep on differentiating $f(x)$ and evaluate the derivatives at 'x'.

If the first non-zero derivative occurs at an odd order

(like 3), (be it +ve or -ve) then 'x' is a **point of inflection**.

If the first non-zero derivative occurs at an even order (say $n = 2$), then there is **either a max., or a min.** at 'x'.

If $f^n(x) < 0$, it's a max., if $f^n(x) > 0$, it's a min.



Examples :

1. **$f(x) = x^2 \Rightarrow f'(x) = 2x$.** So, $f'(x) = 0$ at $x = 0$.
 $f''(x) = 2$ at $x = 0$ (actually, at all points) $\Rightarrow x = 0$ is a minimum point.
2. **$f(x) = 10 - x^2 \Rightarrow f'(x) = -2x$.** So, $f'(x) = 0$ at $x = 0$.
 $f''(x) = -2$ at $x = 0$ (actually, at all points) $\Rightarrow x = 0$ is a point of maxima.
3. **$f(x) = x^3 \Rightarrow f'(x) = 3x^2$.** So, $f'(x) = 0$ at $x = 0$.
 $f''(x) = 6x = 0$ at $x = 0 \Rightarrow f'''(x) = 6$ (non-zero at 3rd order) at $x = 0$
 $\Rightarrow x = 0$ is a point of inflection.

4. $f(x) = x^4 \Rightarrow f'(x) = 4x^3$. So, $f'(x) = 0$ at $x = 0$.
 $f''(x) = 12x^2 = 0$ at $x = 0 \Rightarrow f'''(x) = 24x = 0$ at $x = 0$
 $\Rightarrow f''''(x) = 24$ (non-zero at 4th order) at $x = 0$, hence, $x = 0$ is a minimum point.

Function of a two variables

Two dimensional Taylor Expansion :

$$f(x+h, y+k) = f(x, y) + \{h f_x(x, y) + k f_y(x, y)\} + \{h^2 f_{xx}(x, y) + k^2 f_{yy}(x, y) + 2hk f_{xy}(x, y)\} / 2! + \dots$$

In this case, if the function has a (local) maximum or minimum at a point (x, y) then the value of the function should be stationary within a small patch around the point (x, y) .

Upto 1st order :

$$f(x+h, y+k) = f(x, y) \Rightarrow f_x(x, y) = 0, f_y(x, y) = 0, \text{ if } x \text{ and } y \text{ are independent variables.}$$

To find whether there is a maximum or minimum at this point, we are to evaluate the

Hessian determinant :

$$\begin{vmatrix} f_{xx} & f_{xy} \\ f_{yx} & f_{yy} \end{vmatrix} = (f_{xx} f_{yy} - f_{xy}^2) = H.$$

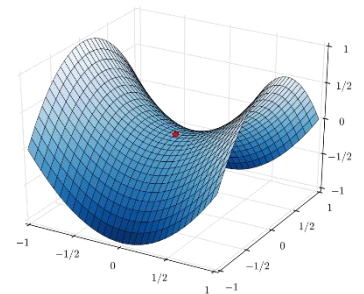
If $H > 0$, and $f_{xx} > 0$, the point (x, y) is a **minimum point**;

if $H > 0$, and $f_{xx} < 0$, the point (x, y) is a **maximum point**;

if $H = 0$, no such conclusion can be drawn

and if $H < 0$, the point (x, y) is a **'saddle point'**.

A saddle point is one which is maximum along one axis and minimum along another. Typical example is the point at the middle of a horse' saddle (hence the name).



Constrained Maxima/Minima

Lagrange' s Method of Undetermined Multiplier

Suppose you are given a function of several variables $f(x, y, z)$ and you are to find the maxima / minima of the function, subject to one or more **'constraints'** of the form $\phi(x, y, z) = \text{const.}$ (The number of variables – the number of constraints) is usually called the **'degrees of freedom'**.

Since at the extremum point, the function is locally stationary,

$$df(x,y) = 0 \Rightarrow f_x dx + f_y dy + f_z dz = 0 \text{ ---- (1)}$$

However, dx, dy, dz are not independent here, because of the constraint. So, we cannot equate their coefficient to zero.

$$\phi(x, y, z) = c \Rightarrow d\phi(x, y, z) = 0 \Rightarrow \phi_x dx + \phi_y dy + \phi_z dz = 0 \text{ ---- (2)}$$

Multiply eqn.(2) by some constant ' λ ' (which is not determined so far) and add with eqn.(1) :

$$\Rightarrow \{f_x + \lambda \phi_x\} dx + \{f_y + \lambda \phi_y\} dy + \{f_z + \lambda \phi_z\} dz = 0 \text{ ---- (3)}$$

Since we have three variables and one constraint here, the number of independent variables = 2.

We may choose, say as x and y as the independent ones. Now we adjust ' λ ' to make the coefficient of $dz = 0$, i.e.,

$$f_z + \lambda \phi_z = 0 \text{ ---- (4)}$$

[which is possible by making $\lambda = -f_z / \phi_z$]

Now, eqn. (3) $\Rightarrow \{f_x + \lambda \phi_x\} dx + \{f_y + \lambda \phi_y\} dy = 0$,

where dx and dy are chosen as independent. **So, now we can equate their coefficient to zero.**

$$\Rightarrow f_x + \lambda \phi_x = 0 \text{ ---- (5)}$$

$$f_y + \lambda \phi_y = 0 \text{ ---- (6)}$$

Solving (4), (5) and (6), together with the constraint eqn. $\phi(x, y, z) = c$, we can find x, y, z and also λ . If we have two constraints, say $\phi(x, y, z) = c_1$ and $\psi(x, y, z) = c_2$, then :

$$d\phi(x, y, z) = 0 \Rightarrow \phi_x dx + \phi_y dy + \phi_z dz = 0 \text{ ---- (7)}$$

$$d\psi(x, y, z) = 0 \Rightarrow \psi_x dx + \psi_y dy + \psi_z dz = 0 \text{ ---- (8)}$$

Multiplying eqn.(7) by ' λ ' and (8) by ' μ ' and adding with eqn.(1) :

$$\Rightarrow \{f_x + \lambda \phi_x + \mu \psi_x\} dx + \{f_y + \lambda \phi_y + \mu \psi_y\} dy + \{f_z + \lambda \phi_z + \mu \psi_z\} dz = 0 \text{ ---- (9)}$$

Now, only one variable is independent say 'x'. We can adjust ' λ ' and ' μ ' to make :

$$f_y + \lambda \phi_y + \mu \psi_y = 0 \text{ ---- (10)}$$

$$\text{and } f_z + \lambda \phi_z + \mu \psi_z = 0 \text{ ---- (11)}$$

[which is possible by solving eqns. (10) and (11) for λ and μ]

Then, equating the coefficient of 'dx' to zero we get :

$$f_x + \lambda \phi_x + \mu \psi_x = 0 \text{ ---- (12)}$$

So, we shall need to solve eqns (10), (11), (12), together with the two constraint equations :

$\phi(x, y, z) = c_1$ and $\psi(x, y, z) = c_2$, to find x, y, z, λ and μ .

Examples :

1. Maximize the area of a rectangle formed by a string of fixed length 'L'.

Let the sides of the rectangle be x and y. Then, area $A = xy$ and the perimeter $= 2(x + y) = L$.

$$\Rightarrow \partial A / \partial x + \lambda \partial L / \partial x = y + 2\lambda = 0$$

$$\partial A / \partial y + \lambda \partial L / \partial y = x + 2\lambda = 0$$

$\Rightarrow x = y$. i.e. the rectangle must be a square.

Substituting in the constraint eqn. : $4x = L \Rightarrow x = L/4$.

2. Maximize the volume of a rectangular parallelepiped, subject to the constraint that its total surface area is constant.

Let the sides of the parallelepiped be x, y and z. Then, its volume $V = xyz$ and the surface area $S = 2(xy + yz + zx) = \text{const.}$

$$\Rightarrow V_x + \lambda S_x = 0 \Rightarrow yz + 2\lambda (y + z) = 0 \text{ ---- (a)}$$

$$V_y + \lambda S_y = 0 \Rightarrow xz + 2\lambda (x + z) = 0 \text{ ---- (b)}$$

$$V_z + \lambda S_z = 0 \Rightarrow xy + 2\lambda (x + y) = 0 \text{ ---- (c)}$$

Multiply eqn. (a) by x and eqn.(b) by y and subtract :

$$\Rightarrow 2\lambda (xz - yz) = 0 \Rightarrow x = z$$

Similarly, we can show that $y = z$ and $z = x$.

$$\Rightarrow S = 2(xy + yz + zx) = 6x^2$$

$$\Rightarrow x = \sqrt{(S/6)}, \text{ in terms of the given data.}$$